

Overview and Impact

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WHY ROBOFOOT

- Lack of automation:
 - The high number of products
 variants
 - Complex manufacturing process
 - Complex assembly process
 - *Manual* quality control and packaging







Scientific Objectives

- New programming approaches
 - CAD and sensor based programming
 - Manual guidance devices for PBD
- Sensor based control strategies
 - Force control based real time trajectory adjustment
 - Visual servoing: To control the position of the robot's end-effector relative to the shoe
 - Intelligent engine able to select and implement the best control strategy for each application
- Manipulation
 - Strategies and devices for rigid and non-rigid parts manipulation
- Footwear Manufacturing
 - Process control
 - Quality assurance



Consortium



60% of Industrial partnership



Societal and economic impact

- To contribute to European Footwear competitiveness by the introduction of robotics
 - To enhance final product quality. To achieve 100% inspection of final product (over certain aspects).
 - To allow more flexible production lines to answer small production batches.
 - To reduce assembly costs.
 - Compatibility with current production means and procedures
- To obtain better working conditions for workers
 - Dust and chemical products
 - Rotating machinery in some manual operations
 - Human force needed in some operations (Last Opening)